

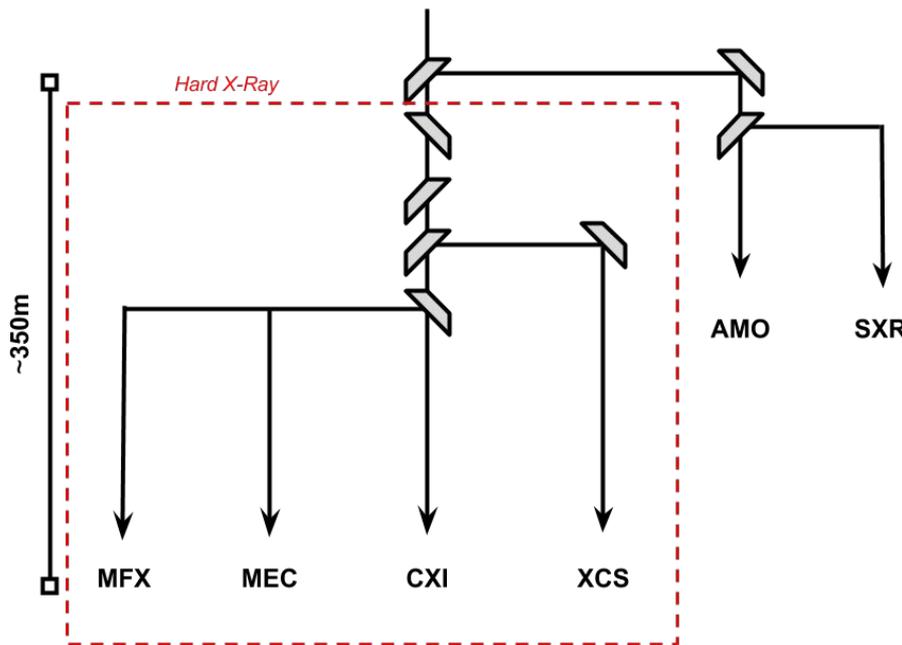
Skywalker

Automated Alignment at LCLS

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Motivation for Automatic Mirror Alignment

- Seven experimental hutches, each requiring unique pointing of flat mirror systems
 - Each with sensitive downstream optics
 - Common for experiments to run in serial
- LCLS-II upgrade in 2019 adds more mirrors and more endstations
 - Emphasis on automation



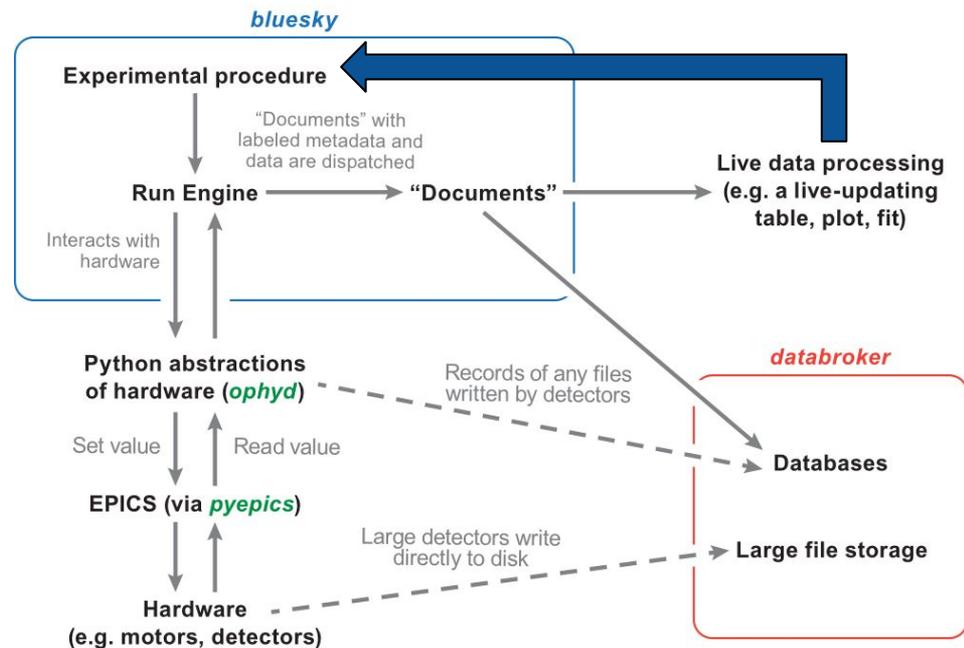
- **Set positions and pre-alignment are not good enough**
 - Pointing of the FEL is not repeatable enough for `set and forget` values
 - No diagnostics sensitive enough to determine undulator pointing for optics 350m away
 - Over 190 devices in the common areas of the beamline
- **Skywalker Deliverables**
 - Operators should be able to `single-click` align to any of Hard X-Ray endstations
 - Should be done faster than manual alignment (or time claimed by operators for manual alignment)
 - Deal with dynamic target selection
 - Full automation
 - Watch for drops in FEL energy
 - Clear the beamline of obstructions
 - Durable against day to day operation
 - Create a suite of tools for future automation projects

- Flat Mirror System
 - Controlled by ELMO Drives with a Beckhoff PLC Ethercat Master
 - Stepper and piezo in series on the pitch mechanism
- 4 Jaw-Slits
 - Produced by JJ-XRAY
 - Use EPICS motor record
- Imagers
 - YAG crystal fluoresces when X-Rays are incident
 - EPICS AreaDetector
- Software
 - Python 3.5 and up
 - Ophyd and Bluesky



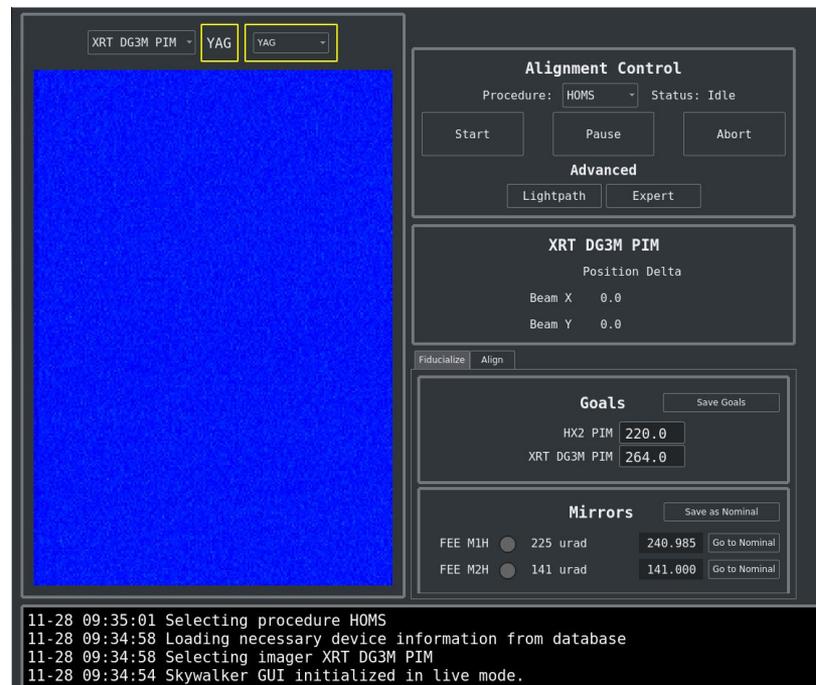
Bluesky and Automation: Motivation

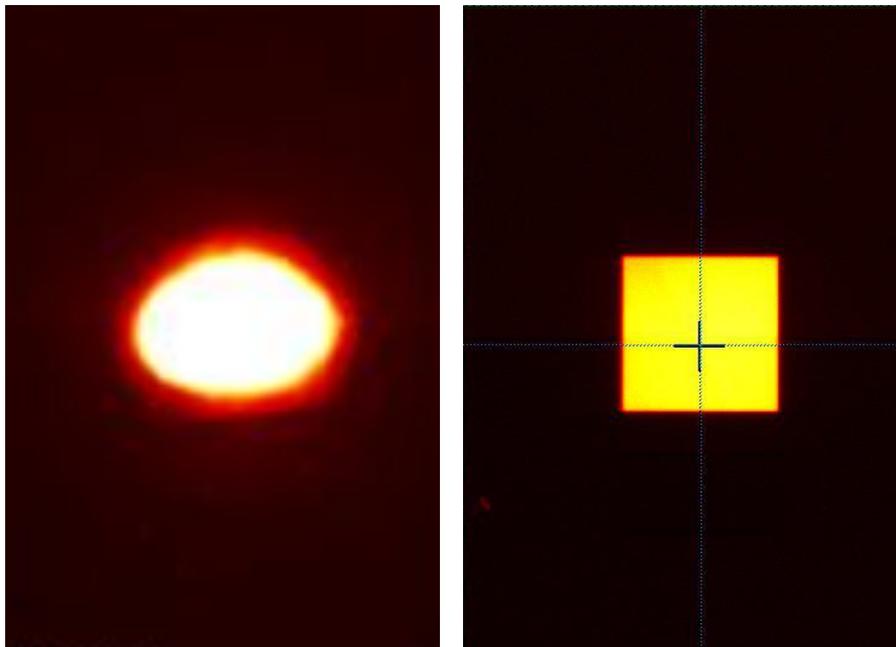
- An appealing combination because we already have Ophyd devices
- Bluesky provides flow control
 - Start, stop, pause, rewind, resume, suspend
- Bluesky has an interface that lends itself well to re-using well-tested code in new ways.
 - Use documents interface to feed information back into the plan



PyDM User Interface

- Allows user to select procedure
 - Select hutch for beam delivery
 - Tune tolerances and averaging
- Full control of RunEngine
- Live feedback for mirror and imager systems
- Displays logging output

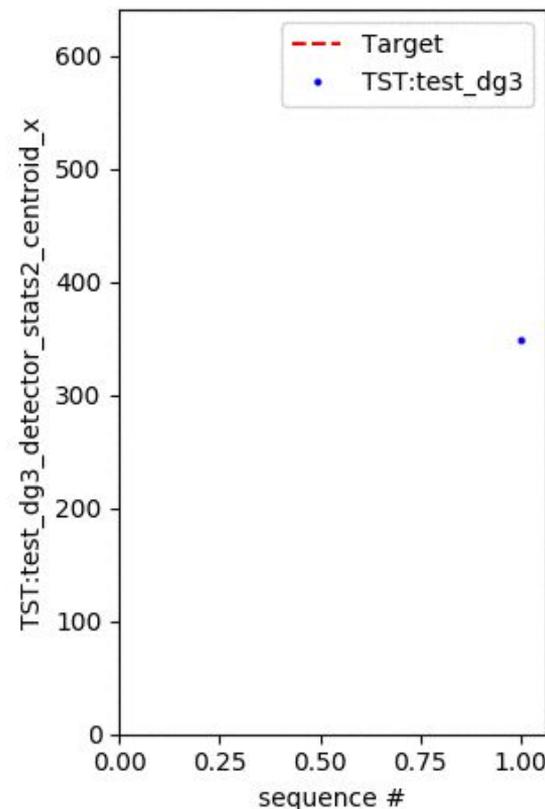
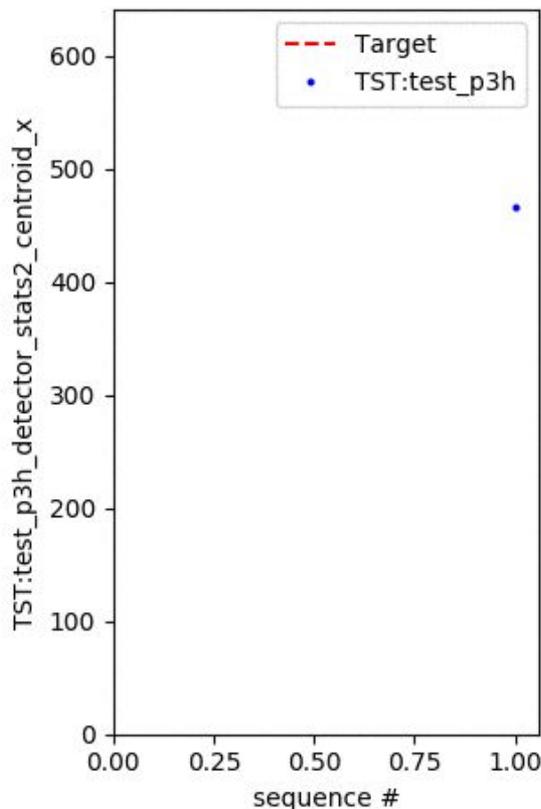




- Fiducialize imager by using previously aligned 4-Jaw slits
 - Trim the beam down to only a small subsection that is aligned
 - Calculate the centroid of this subsection
 - Expand slits and difference between the open and closed centroid is the error in our pointing
 - Fiducialization at 2 points defines our target beam axis

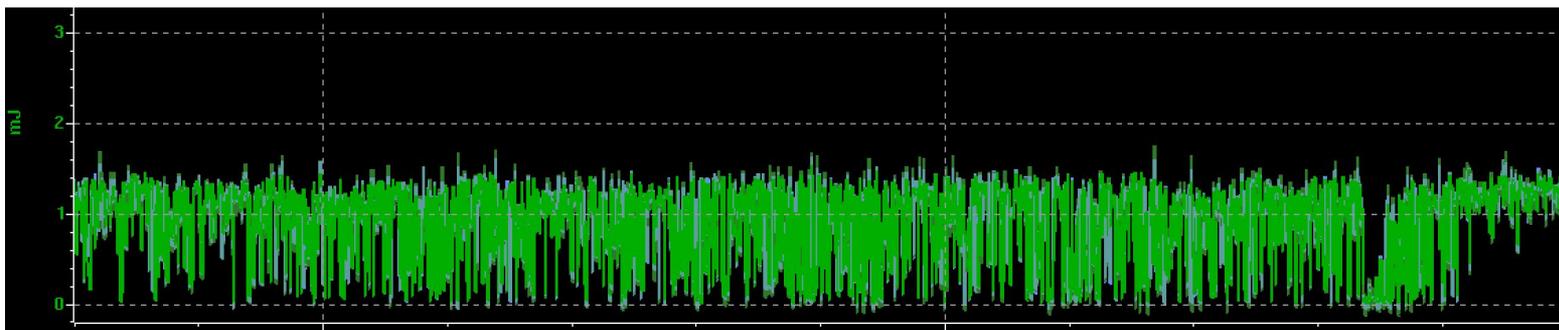
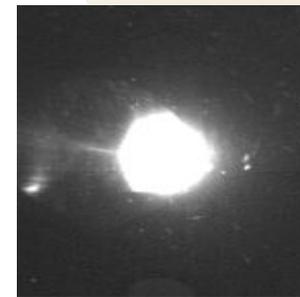
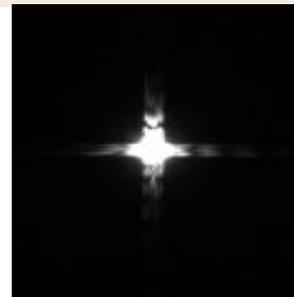
2-Mirror Alignment Procedure

- Basic iterative process
- Match first mirror to a near imager, second mirror to a far imager
- Align each mirror-imager pair to their goal pixel, which slightly misaligns the other pair. Repeat.
- Use linear fit to minimize number of steps
- Take average of many blueky reads from the area detector beam centroid after each move



Hurdles: It's never easy

- Unstable FEL
 - Heavy use of Bluesky suspenders
 - Bad events must be filtered
- Optical Phenomena
 - Sometimes, more complex image filtering may be needed... but you may not know until taking beam.



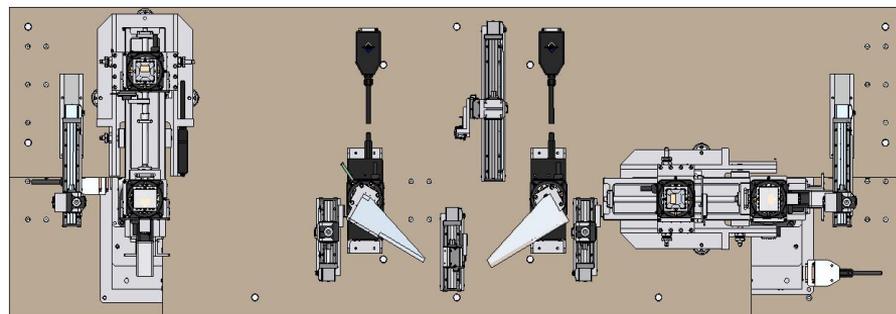
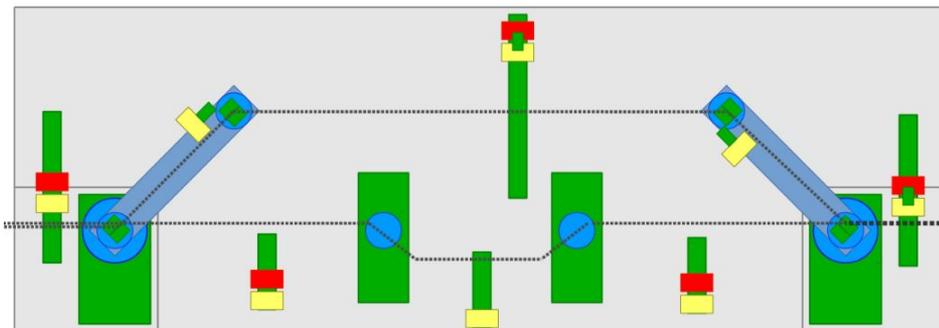
- Single Mirror Alignment
 - No prior knowledge
 - Capable of pixel precision (3.4 μm)
 - Accomplished in roughly 60 seconds
 - Majority of time spent during fine adjustment
 - Within 10 pixel tolerance after first step
 - [Jupyter Notebook](#)
- Two Mirror Alignment
 - Able to reliably find solutions within a pixel
 - Starting with no prior knowledge, no beam on imagers
 - 7 minutes
 - Seeding the run with approximate values
 - 2 minutes

Bluesky and Automation: The Verdict

- Bluesky is well-suited to procedures that need both dynamic flow control and data feedback.
 - Similar level of complexity as doing it functionally, but you get a lot of extra control in a clean way.
 - No need to implement your own interrupt handler, your own pause/resume, your own device abstraction schema...
- Can re-use any of the data collection and visualization code
- There is room for growth
 - Suspenders are powerful and have huge potential for new features e.g. message-dependent suspension
 - We've only scratched the surface of adaptive plans

Follow-up Project: Split and Delay

- LCLS installed a new Split and Delay assembly
- Delay line is sensitive to small transverse errors: these have strong effects on the beam overlap.
- Re-used code from Skywalker to automatically calibrate for repeatable transverse error in the delay branches
 - Use extra rotation axis to correct for the pointing error
- With the calibration, we can quickly scan across delay intervals.



Related Upcoming Projects

- Automated mirror centering
- Automated lens focusing
- Automated laser/x-ray overlap, with specified laser parameters tuned automatically
- Record data from alignment routines to optimize the alignment and analyze beam statistics over time

Documentation

- <https://pswww.slac.stanford.edu/swdoc/releases/skywalker>
- <https://nsls-ii.github.io/ophyd>
- <https://nsls-ii.github.io/bluesky>

Source

- <https://github.com/slaclab/skywalker>
- <https://github.com/slaclab/pswalker>
- <https://github.com/slaclab/lightpath>
- <https://github.com/slaclab/happi>
- <https://github.com/slaclab/psbeam>
- <https://github.com/NSLS-II/ophyd>
- <https://github.com/NSLS-I/bluesky>

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